

1. FUNDAMENTAL SOLUTION

The function $\Phi : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}$

$$\Phi(x) = \begin{cases} -\frac{1}{2\pi} \log |x| & n = 2, \\ \frac{1}{(n-2)\omega_n |x|^{n-2}} & n \geq 3, \end{cases}$$

is called the fundamental solution for the Laplace operator, where ω_n denotes the surface area of the unit sphere in \mathbb{R}^n . For example, $\omega_3 = 4\pi$.

We can easily check that $\Delta\Phi(x) = 0$ holds for $x \neq 0$.

2. NEWTONIAN POTENTIAL

Given a smooth function $f : \mathbb{R}^n \rightarrow \mathbb{R}$, we call the following function the Newtonian potential of f .

$$u(x) = \int_{\mathbb{R}^n} \Phi(x-y)f(y)dy. \quad (1)$$

Theorem 1. *Suppose that a smooth function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ satisfies $f(x) = 0$ if $|x| \geq M$ for some constant M . Then, the potential function (1) satisfies*

$$\Delta u(x) = -f(x). \quad (2)$$

We only consider the $n = 2$ case for the purpose of simplicity. The higher dimensions can be similarly shown.

Proof for the two dimension. By using the substitution $y - x = z$, we have

$$u(x) = \int_{\mathbb{R}^2} \Phi(x-y)f(y)dy = \int_{\mathbb{R}^2} \Phi(z)f(x+z)dz.$$

Hence,

$$\Delta u(x) = \int_{\mathbb{R}^2} \Phi(z)\Delta_x f(x+z)dz = \int_{\mathbb{R}^2} \Phi(z)\Delta_z f(x+z)dz = I_\epsilon + J_\epsilon,$$

where $\epsilon < M$ is a small constant and

$$I_\epsilon = \int_{B_M(0) \setminus B_\epsilon(0)} \Phi(z)\Delta_z f(x+z)dz,$$

$$J_\epsilon = \int_{B_\epsilon(0)} \Phi(z)\Delta_z f(x+z)dz.$$

The integration by parts implies

$$I_\epsilon = K_\epsilon - \int_{B_M(0) \setminus B_\epsilon(0)} \nabla_z \Phi(z) \nabla_z f(x+z) dz.$$

where

$$K_\epsilon = \int_{\partial B_M(0) \cup \partial B_\epsilon(0)} \Phi(z) \partial_\nu f(x+z) dz = \int_{\partial B_\epsilon(0)} \Phi(z) \partial_\nu f(x+z) dz.$$

We again apply the integration by parts.

$$I_\epsilon - K_\epsilon = H_\epsilon + \int_{B_M(0) \setminus B_\epsilon(0)} \Delta_z \Phi(z) f(x+z) dz.$$

where

$$H_\epsilon = - \int_{\partial B_M(0) \cup \partial B_\epsilon(0)} \partial_\nu \Phi(z) f(x+z) dz = - \int_{\partial B_\epsilon(0)} \partial_\nu \Phi(z) f(x+z) dz.$$

Since $\Delta_z \Phi(z) = 0$ for $z \neq 0$, we have

$$\Delta u(x) = J_\epsilon + K_\epsilon + H_\epsilon.$$

Next, by using $|\Delta f| \leq C$ we have

$$\lim_{\epsilon \rightarrow 0} |J_\epsilon| \leq C \lim_{\epsilon \rightarrow 0} \int_{B_\epsilon(0)} \Phi(z) dz \leq C \lim_{\epsilon \rightarrow 0} \int_0^{2\pi} \int_0^\epsilon \frac{-\log r}{2\pi} r dr d\theta = 0.$$

Also, $|\nabla f| \leq C$ implies

$$\lim_{\epsilon \rightarrow 0} |K_\epsilon| \leq C \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(0)} \Phi(z) dz = -C \lim_{\epsilon \rightarrow 0} \frac{2\pi\epsilon \log \epsilon}{2\pi} = 0.$$

On the other hand, on $\partial B_\epsilon(0)$ we have

$$\partial_\nu \Phi(z) = \left\langle -\frac{z}{2\pi|z|^2}, \nu \right\rangle = \frac{|z|^2}{2\pi|z|^3} = \frac{1}{2\pi\epsilon}.$$

Therefore,

$$f(x) + \lim_{\epsilon \rightarrow 0} H_\epsilon = \int_{\partial B_\epsilon(0)} \frac{f(x)}{2\pi\epsilon} dz - \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(0)} \frac{f(x+z)}{2\pi\epsilon} dz = \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(0)} \frac{f(x) - f(x+z)}{2\pi\epsilon} dz = 0.$$

□

3. GREEN FUNCTION

We assume that there exists a smooth function $\varphi : \Omega \times \Omega \rightarrow \mathbb{R}$ such that for each fixed $x \in \Omega$ the following hold

$$\begin{aligned}\Delta_y \varphi(x, y) &= 0 & y \in \Omega, \\ \varphi(x, y) &= \Phi(x - y) & y \in \partial\Omega.\end{aligned}$$

Then, the function

$$G(x, y) = \Phi(x, y) - \varphi(x, y)$$

is called the Green function. One can easily check $G(x, y) > 0$ for $x, y \in \Omega$ by the maximum principle. Also, we will show $G(x, y) = G(y, x)$ as an assignment in the problem set 3.

In particular, if $\Omega = B_R(0)$ then

$$G(x, y) = \begin{cases} -\frac{1}{2\pi} \left(\log |x - y| - \log \left| \frac{R}{|x|} x - \frac{|x|}{R} y \right| \right) & n = 2, \\ \frac{1}{(n-2)\omega_n} \left(|x - y|^{2-n} - \left| \frac{R}{|x|} x - \frac{|x|}{R} y \right|^{2-n} \right) & n \geq 3. \end{cases}$$

Therefore, the Green's representation formula (6) yields the Poisson's formula

$$u(x) = \frac{R^2 - |x|^2}{\omega_n R} \int_{\partial B_R(0)} \frac{u(y)}{|x - y|^n} dy. \quad (3)$$

In order to show the Green's representation formula, we need the following lemma.

Lemma 2. *Given a smooth bounded domain Ω and a smooth function u , the following holds*

$$u(x) = - \int_{\Omega} \Phi(x - y) \Delta u(y) dy + \int_{\partial\Omega} \Phi(x - y) u_\nu(y) - u(y) \Phi_\nu(x - y) dy. \quad (4)$$

Proof. The integration by parts provides the Green's identity for smooth functions u, v ;

$$\int_{\Omega} (v \Delta u - u \Delta v) dy = \int_{\partial\Omega} v \partial_\nu u - u \partial_\nu v dy. \quad (5)$$

Given a fixed $x \in \Omega$ we define $\Omega_\epsilon = \Omega \setminus B_\epsilon(x)$ for small ϵ . In addition, we define

$$\begin{aligned} J_\epsilon &= \int_{B_\epsilon(x)} \Phi(x-y) \Delta u(y) dy, \\ K_\epsilon &= \int_{\partial B_\epsilon(x)} \Phi(x-y) \partial_\nu u(y) dy, \\ H_\epsilon &= - \int_{\partial B_\epsilon(x)} u(y) \partial_\nu \Phi(x-y) dy. \end{aligned}$$

Then, (5) and $\Delta_y \Phi(x-y) = 0$ in Ω_ϵ yield

$$\int_{\Omega_\epsilon} \Phi(x-y) \Delta u(y) dy = \int_{\partial \Omega_\epsilon} \Phi(x-y) \partial_\nu u(y) - u(y) \partial_\nu \Phi(x-y) dy.$$

Therefore, it is enough to show $\lim_{\epsilon \rightarrow 0} J_\epsilon + K_\epsilon + H_\epsilon = -u(x)$. By using $|\Delta u| \leq C$

$$\lim_{\epsilon \rightarrow 0} |J_\epsilon| \leq C \lim_{\epsilon \rightarrow 0} \int_{B_\epsilon(x)} \Phi(x-y) dy = C \lim_{\epsilon \rightarrow 0} \int_{B_\epsilon(0)} \Phi(z) dz = 0.$$

Also, $|\nabla u| \leq C$ implies

$$\lim_{\epsilon \rightarrow 0} |K_\epsilon| \leq C \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(x)} \Phi(x-y) dy = C \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(0)} \Phi(z) dz = 0.$$

On the other hand, on $\partial B_\epsilon(x)$ we have

$$\partial_\nu \Phi(x-y) = \frac{1}{\omega_n |x-y|^{n-1}} = \frac{1}{\omega_n \epsilon^{n-1}} = \frac{1}{|B_\epsilon|}.$$

where $|B_\epsilon|$ is the surface area of a ball of radius ϵ in \mathbb{R}^n . Therefore,

$$u(x) + \lim_{\epsilon \rightarrow 0} H_\epsilon = \int_{\partial B_\epsilon(x)} \frac{u(x)}{|B_\epsilon|} dy - \lim_{\epsilon \rightarrow 0} \int_{\partial B_\epsilon(x)} \frac{u(y)}{|B_\epsilon|} dy = 0.$$

□

Theorem 3 (Green's representation formula). *Suppose that Ω is a smooth bounded domain and u is a smooth function satisfying*

$$\begin{aligned} \Delta u(x) &= f(x) & x \in \Omega, \\ u(x) &= g(x) & x \in \partial \Omega. \end{aligned}$$

Then, the function $u(x)$ satisfies

$$u(x) = - \int_{\Omega} f(y)G(x, y)dy - \int_{\partial\Omega} g(y)G_{\nu}(x, y)dy. \quad (6)$$

Proof. We apply the Green's identity (5) for $\varphi(x, y)$. Then, $\Delta_y\varphi(x, y) = 0$ implies

$$\int_{\Omega} \varphi(x, y)\Delta u(u)dy = \int_{\partial\Omega} \varphi(x, y)\partial_{\nu}u(y) - u\partial_{\nu}\varphi(x, y)dy.$$

Combining with Lemma 2 yields the Green's representation formula. \square

4. HARNACK'S INEQUALITY

Theorem 4. *Suppose that $\Delta u = 0$ and $u \geq 0$ hold in Ω . Then, for $B_R(z) \subset \Omega$ and $x \in \overline{B_R(z)}$ the following holds*

$$\frac{R^{n-2}(R-r)}{(R+r)^{n-1}}u(z) \leq u(x) \leq \frac{R^{n-2}(R+r)}{(R-r)^{n-1}}u(z). \quad (7)$$

where $r = |x - z|$.

Proof. Without loss of generality, we assume $z = 0$ and thus $r = |x|$. Then, we recall the Poisson's formula

$$u(x) = \frac{R^2 - |x|^2}{\omega_n R} \int_{\partial B_R(0)} \frac{u(y)}{|x - y|^n} dy.$$

Since $R - |x| \leq |x - y| \leq R + |x|$ and $|x| = r$, we have

$$\frac{(R-r)}{\omega_n R (R+r)^{n-1}} \int_{\partial B_R(0)} u(y) dy \leq u(x) \leq \frac{(R+r)}{\omega_n R (R-r)^{n-1}} \int_{\partial B_R(0)} u(y) dy. \quad (8)$$

Hence, the mean value property yields the desired result. \square